

Standard specifications

RA005LFF60001

1st Edition: July 25, 2017

KAWASAKI HEAVY INDUSTRIES, LTD. ROBOT DIVISION

Specification:	90101-2722DEA
(Arm):	90151-0112DEA
(Controller):	90152-0057DEA

1. Specification of Robot

[1] Robot Arm						
1. Model	RA005L-A					
2. Type	Articulated robot					
3. Degree of freedom	6 axes					
4. Axis specification	Operating axis Max. operating range Max. speed					
	Arm rotation	(JT1)	$+180^{\circ} \sim -180^{\circ}$		300 °/s	
	Arm out-in (JT2)		+135 ° ∼ − 80 °		300 °/s	
	Arm up-down (JT3)		+118 ° ~ -172 °		300 °/s	
	Wrist swivel	(JT4)	+360 ° ∼ −360 °		460 °/s	
	Wrist bend	(JT5)	+145 ° ~ -145 °		460 °/s	
	Wrist twist	(JT6)	+360 ° ∼-3	60 °	740 °/s	
5. Repeatability	± 0.03 mm (at the tool mounting surface)					
6. Max. payload	5 kg					
7. Max. speed	9300 mm/s (at the	center of too	mounting surface)			
8. Load capacity of	8. Load capacity of					
wrist		M	ax. torque		Moment of inertia*	
	JT4		12.3 N·m		$0.40 \text{ kg} \cdot \text{m}^2$	
	JT5		12.3 N·m		$0.40 \text{ kg} \cdot \text{m}^2$	
	JT6		7.0 N·m		$0.12 \text{ kg} \cdot \text{m}^2$	
	Note* Each value in this table shows allowable moment of inertia of JT4/JT5/JT6 when max. allowed torque is applied to each axis. If more detailed data is required for your application, please contact Kawasaki.					
9. Driving motor	Brushless AC Servomotor					
10. Working range	See attached draw	ring				
11. Mass	37 kg (without o	ptions)				
12. Color	Munsell 10GY9/1	equivalent				
13. Installation	Floor or Ceiling n					
14. Environment cond.	(Temperature) $0\sim45^{\circ}\text{C}$, (Humidity) $35\sim85\%$, no dew, nor frost allowed					
15. Degree of protection	IP65					
16. Built-in utilities	Pneumatic pipings	s (ϕ 6 × 2 line	1			
17. Options	Shock sensor		Shock sensor made by KHI, Others ()			
	Torch bracket Solenoid valve Mechanical stopper Color Installation		Std. Bracket (350A / 500A), Others ()			
			Double solenoid / Single solenoid valves (3 units max.)			
			Adjustable mechanical stoppers JT1			
			Munsell ()			
			Wall mounting installation			
	Arm installation stand		height 600 mm / 300 mm			
19 Others	Arm installation plate 400 mm × 400 mm Consult Kawasaki about maintenance parts and spare parts.					
18. Others	Consult Kawasaki about mannenance parts and spare parts.					

[2]	[2] Controller					
1.	Model	F60				
2.	Enclosure	Protection level: IP20 Open structure / Direct cooling system *1				
3.	Dimensions	See attached drawing				
4.	Number of controlled	Max.8 axes (standard	6 axes, option 2 axes)		
	axes	,	, 1			
5.	Servo control and	Full Digital Servo Sys	stem			
	drive system					
6.	Type of control	Teach mode Joint, Base, Tool, Fixed Tool (option) operation mode				
		Repeat mode Joint, Linear, Circular (option) interpolation				
7.	Teaching method	Teaching or AS language programming				
8.	Memory capacity	16 MB				
9.	External operation	External Emergency stop, External Hold, etc.				
	signals					
10.	Number of	2 slots				
	Option board slots					
11.	Operation panel	Teach/Repeat SW, En	nergency Stop SW			
12.	Communication I/F	Ethernet		2port		
		(1000BASE-T/100BA	SE-TX/10BASE-T)			
		USB2.0		3port		
		RS-232C		2port		
_	Mass	See attached drawing				
14.	Power requirement	AC200 V - AC230 V	±10%, 50/60 Hz, 1 ph	ases,		
		Max. 2.0 kVA				
15.	Ground	Less than 100 Ω (rob				
		Leakage current: max	. 100 mA			
	Ambient temperature	0 - 45℃				
	Relative humidity	35 - 85 % (non-conde				
	Color	Munsell: 5Y8.5/1 equ				
19.	Teach Pendant	TFT color display (5.7 inch LCD) with touch panel				
20	a c at t	Emergency Stop SW, Teach Lock SW and Enable SW				
	Safety Circuit Number of General	Category: 4, Performance Level: e (EN ISO13849-1) *2				
21.	purpose I/O signals	IN:16 OUT:16 with an I/O connector	(50nin with gover)			
22	Standard Options	with all 1/O connector	. (30piii with cover)			
22.	Arc Interface	Arc interface add-on b	oard			
	TP sheet language	English or Japanese o				
	Power/Signal cable	5m, 10m, 15m	i Cillicac			
	Teach Pendant cable	5m, 10m, 15m				
23	Other Options	JIII, 10III, 1JIII				
23.	Number of additional	Inside Controller	I/O hoard	d(IN:32 OUT:32) ···up to 2 boards		
	I/O signals	Remote I/O		//O unit(IN:32 OUT:32) · · · up to 4 units		
	2.0016111110	Total max I/O number		`		
	Intake Filter			et into the controller from intake FAN		
	Enclosure			Indirect cooling system (Ambient temperature 0 - 45 °C) *3		
	Motor brake release	Manual brake release switch BOX				
	PC cable (RS-232C)	1.5 m, 3 m				
	External axes control	Additional amplifier and harnesses for external axes				
	Extended safety functions	Cubic-S(Motion area monitoring, Joint monitoring, Speed monitoring etc.) *3				
	Teach Pendant option	Connector for TP less				
	Fast check mode	Fast check mode Switch				
	Others	Field BUS, Software PLC, Analog input/output,				
		Conveyor Synchronization, Bluetooth				
24.	Others	ers Consult Kawasaki about maintenance parts and spare parts.				

NOTE*1

Cooling of the electronic components in this open construction F60 controller is achieved by circulation of ambient air.

The enclosure is designed to protect personnel from coming in contact with hazardous parts inside the controller.

There is no protection to less than 10 mm of alien substance and water.

Please consider ①② and ③ and select the option about protection to the environmental specification

- ①There is no or few non-conductive dusts & particles(influence for the controller is little) · · · Option is not needed.
- There is high possibility that non-conductive dusts & particle will get into controller. ••• Select the option intake Filter or Enclosed structure
- There is high possibility that conductive dusts & particle will get into controller.
 Select the option Enclosed structure
- *For Arc welding, when a rack for dust-proof can't be prepared by a customer, add the Enclosed structure option to the controller.

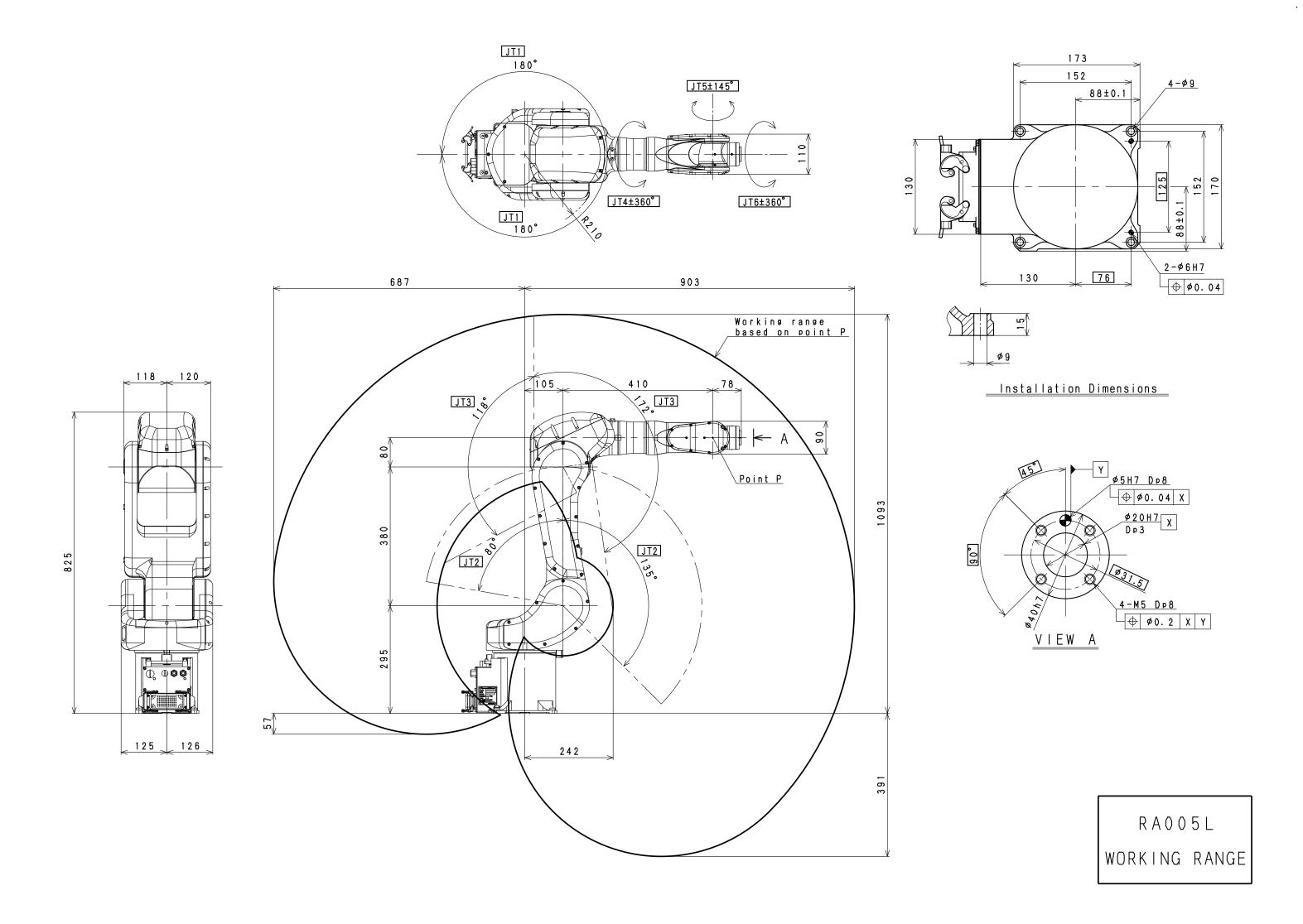
NOTE*2

Category and Performance level (PL) are determined by the whole system and conditions.

The safety circuit of this controller is available in the system of category: up to 4, PL: up to e.

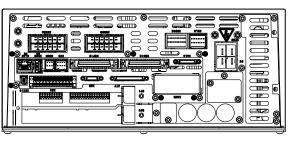
NOTE*3

Attaching additional unit makes size of a controller larger.

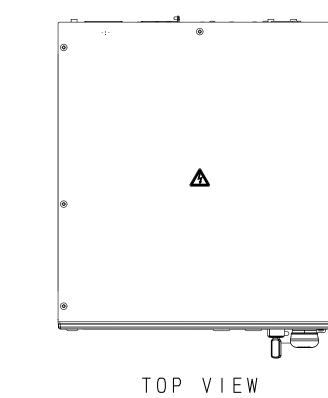


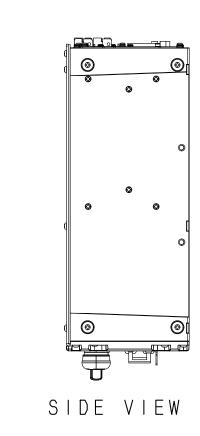
CONTROLLER F 6 0

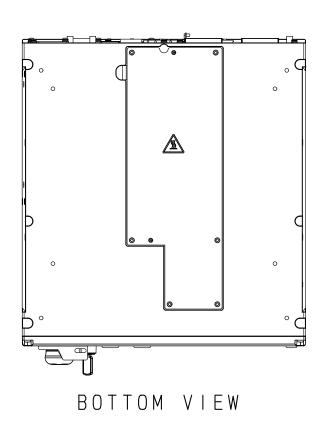
MASS: 8. 5 Kg (Without any options)

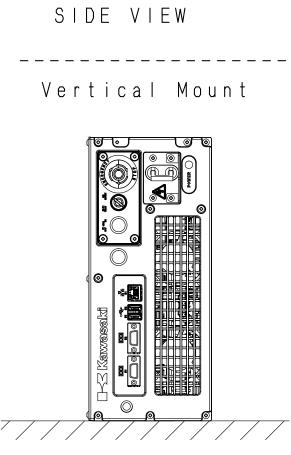


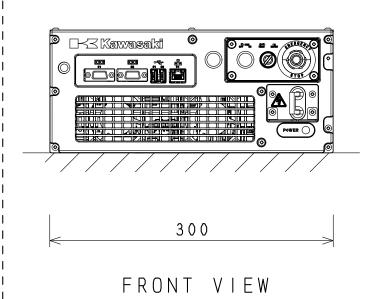
REAR VIEW

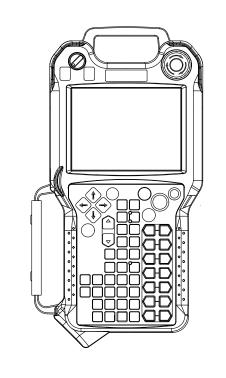




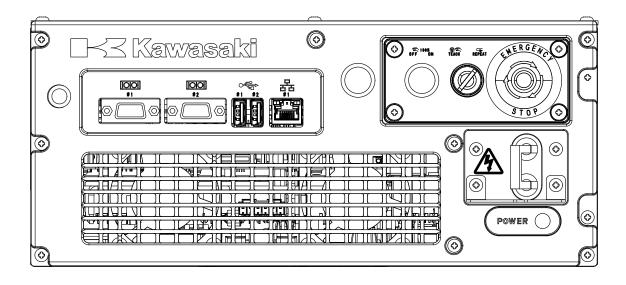




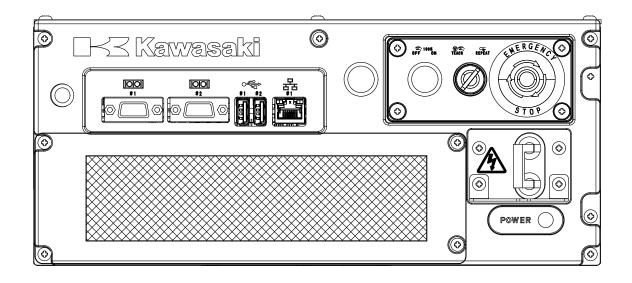




O O pen Structure Standard



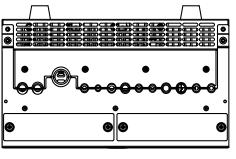
②Open Structure With Intake Filter



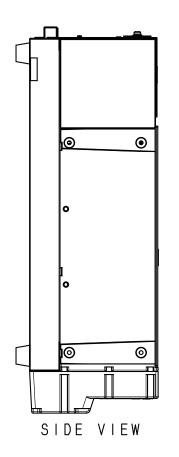
F60 CONTROLLER

MASS: 16Kg

(With Enclosed Structure option)



REAR VIEW



Vertical Mount

